

Use of Small Unmanned Aerial Vehicles for Air Quality and Meteorological Measurements

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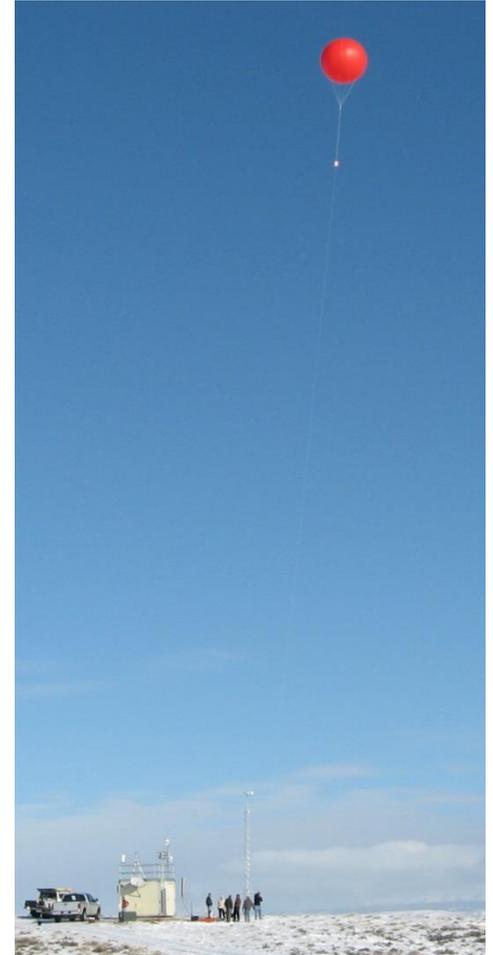


Overview

- Goals for platform development
- UAV types
- Challenges in using UAVs
- Use of new generation lightweight sensors
- Platform development and testing
- Key features as a sampling platform
- Demonstrated uses
- Advanced sampling techniques in development
- Future developments

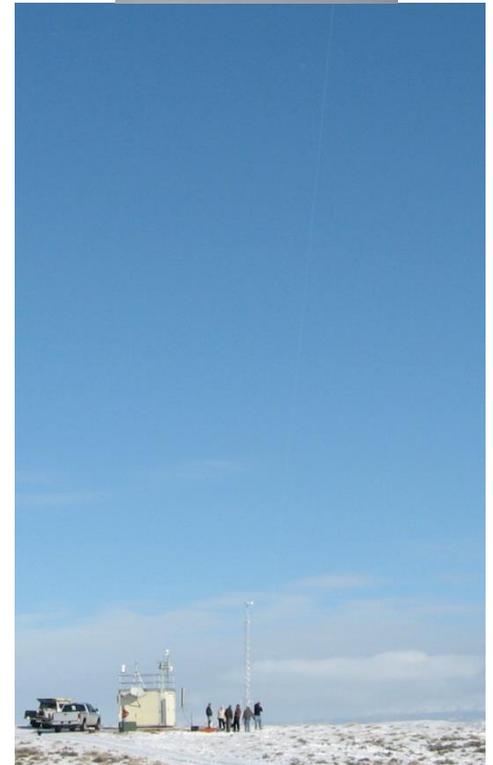
Goals for platform development

- Replace tethered and/or free-flight sampling techniques
- Provide a stable, high precision X-Y-Z platform, for sample collection
- Provide adequate flight time for various integrated and time series data collection missions
- Provide real-time data links and imaging
- Develop autonomous methods for sample collection



Goals for platform development

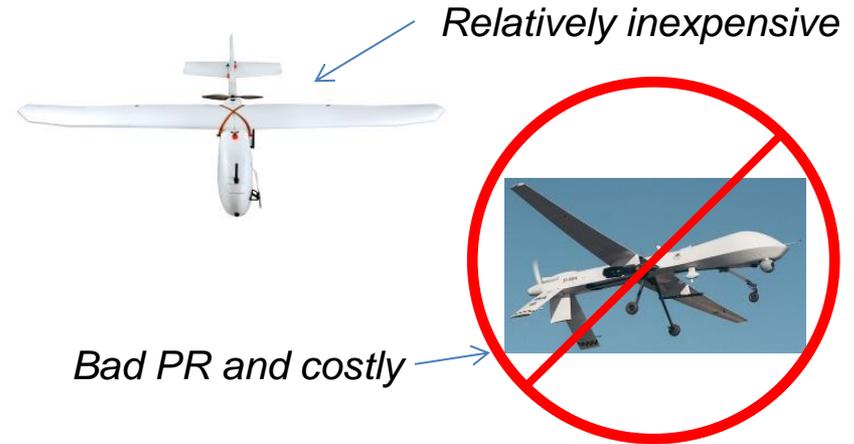
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UAV Types

- Fixed wing

- Larger payload
- Must remain in X-Y motion
- No hover sampling mode



- Multi-rotor

- Smaller payload
- Sampling in motion or fixed
- Extremely stable positioning



Our choice based on development platform

Challenges in using UAVs

- Public Perception

- Privacy concerns driven by emotions
- The word “DRONE” has a real negative first impression
- For acceptance as a research tool, showing the benefits are essential

Close encounters on rise as small drones gain in popularity -- *Washington Post*

Video-seeking drone ordered out of fire area -- *USA Today*

Drone wars: The definition dogfight -- *ABC*

Increasing drone use raises privacy concerns -- *CBS News*

Drones, Accidents, and Secrecy -- *ACLU*

- FAA Restrictions
- Technical



Challenges in using UAVs

- Public Perception
- FAA Restrictions
 - Aviation interference is a primary concern
 - Safety and protection of property is driving additional concerns
 - Hobbyist flight rules currently govern the use of small UAVs and legally limit the commercial use unless a COA is obtained

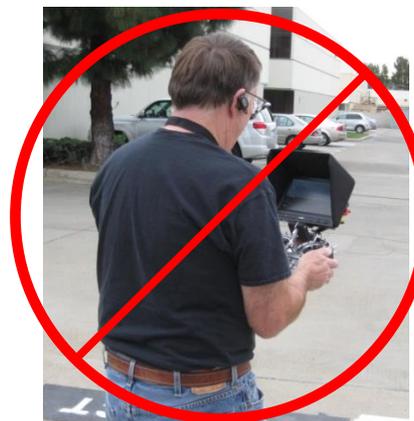
Recreational flying

Model aircraft



Commercial flying

Drone



- Technical

Challenges in using UAVs

- Public Perception
- FAA Restrictions
- Technical
 - RF sensitivity of components can create flight issues with shielding needed to minimize the effects
 - UAV electronics and RF may interfere with some instruments that are not well shielded
 - Vibration effects can impact some instruments
 - Technology explosion from overseas provides very capable systems but with very limited and/or incomplete documentation

Use of New Generation Lightweight Sensors

- Meteorological measurements
 - Temperature, relative humidity, pressure, winds (using GPS)
- Continuous gas measurement
 - Ozone and other gases
- Particulate matter measurement
 - Filter based
 - Real-time
- Integrated gaseous sampling
 - Sorbent tube for VOCs and multiple integrations
 - Canister sampling, but limited by canister weights

Platform Development and Testing

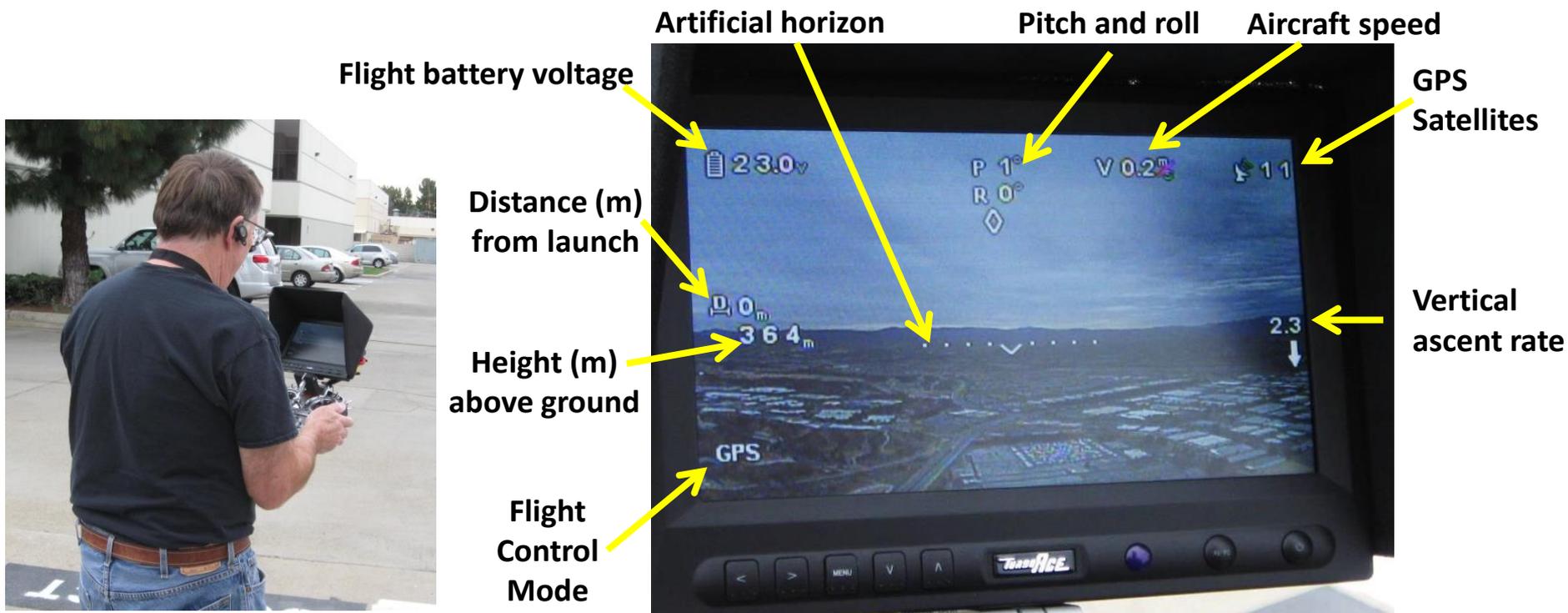
- Platform development
 - Commercially available platform as a foundation
 - Carbon fiber, aluminum and stainless steel hardware
 - All electric to minimize emissions and vibration
 - Vibration dampening components for videography and stability of sampling components
- Initial tests
 - Over 700 meters for meteorological soundings
 - High winds > 10 m/s to 300 meters with gas sampling
 - Flight times to 30 minutes

Key Features as a Sampling Platform

- Lightweight design for easy portability
- Quick setup and deployment
- Automated retrieval in the event of flight control failure
- 2-3 pound payload capacity
- Flight time up to 30 minutes depending on payload
- Accurate GPS positioning with pressure-altitude
- Real-time telemetry of key information
- Real-time video broadcast with data overlay
- High definition video documentation
- Relatively large equipment mounting platform

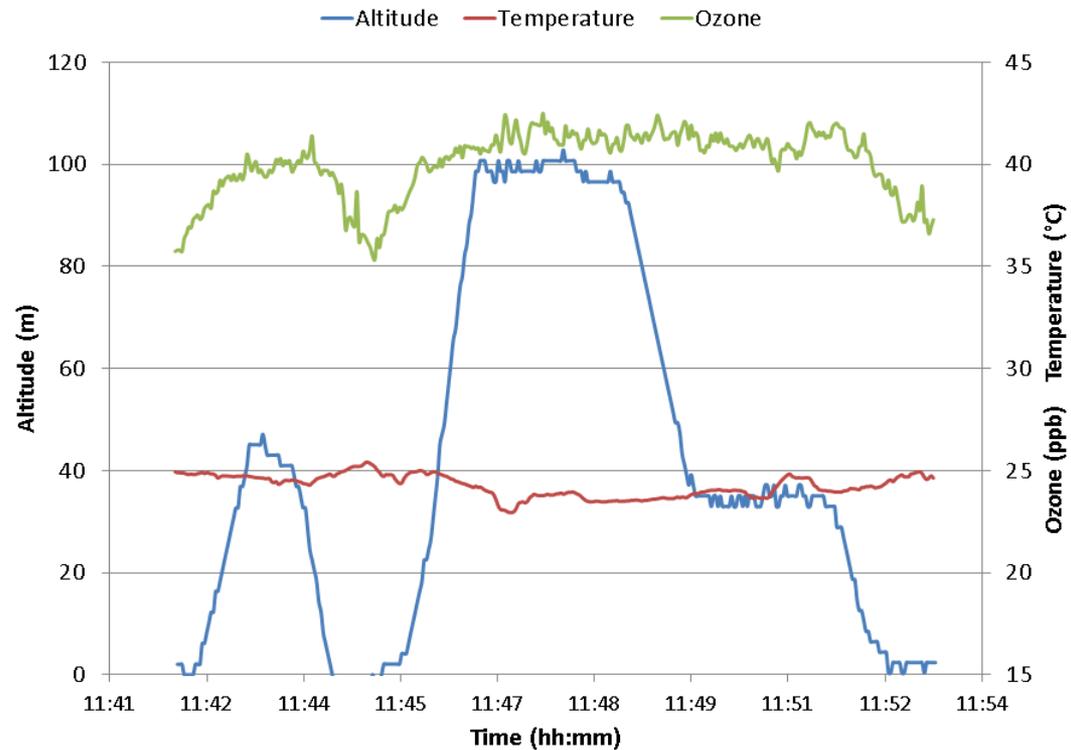
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Demonstrated Uses

- Ozone sampling using a KI ozone sampling system
 - Performed during high winds (>10 m/s) – well mixed

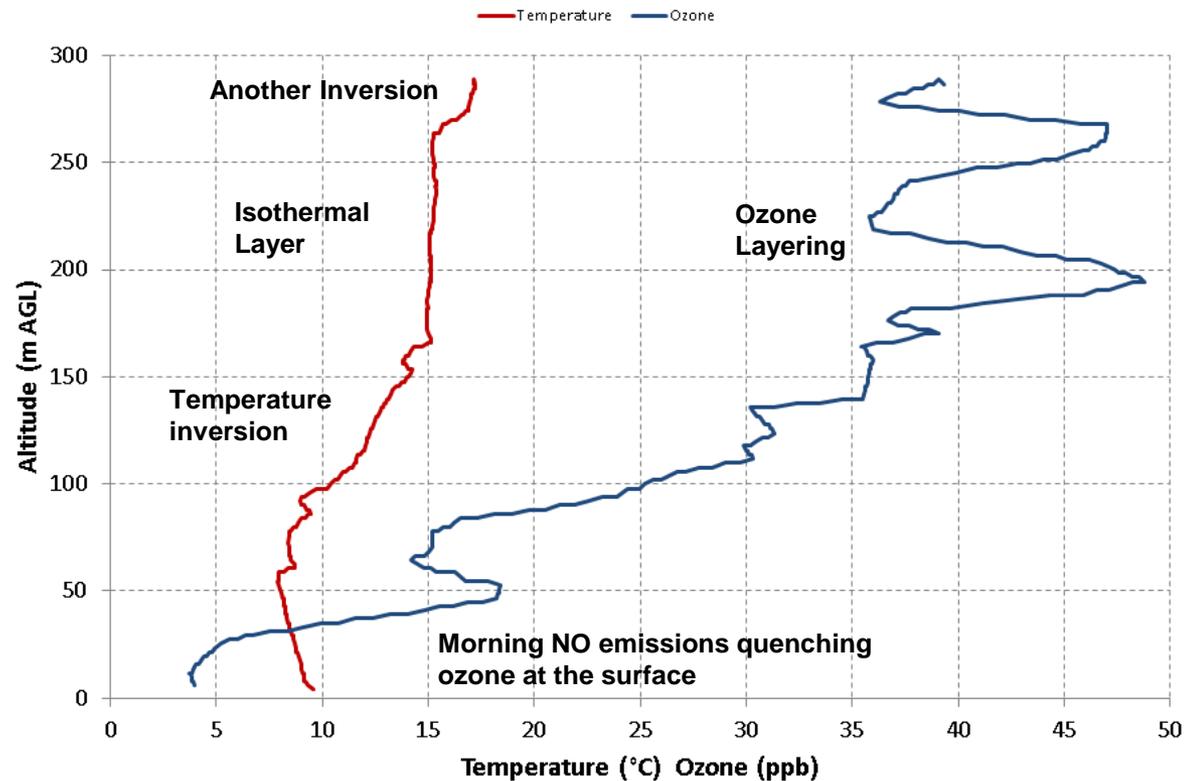


Demonstrated Uses

- Ozone sampling using 2B Personal Ozone Monitor



Quadcopter Temperature and Ozone Sounding Using 2B POM



Advanced Sampling Techniques in Development

- Remotely triggered sampling events
- Pre-programmed flight paths and waypoints
- Wind measurements using GPS stability control with measured pitch and roll
- Wind measurements using platform drift (gyro stabilization only)
- Real-time telemetry of measurements for sampling strategy modification
- Plume profiling with real-time displays
- Fence-line monitoring

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dji DJI Ground Station 4.0

Joystick ToolBox Sys_set Language(□) Help Real Mode

Enter goto location **FLY TRACE** **PATHEXTRUDE** **MAP DETAILS** **INSTRUMENT BOARD** **EDITOR** **CONTINUE** **PAUSE** COM1 **CONNECT**

Aircraft NORTH LATI: 038.6904849 WEST 120.7020014 ALTI: 0000.0 M One Key Takeoff Home Point NORTH LATI: N/A WEST N/A ALTI: 0000.0 M **dji EDITOR**

dji

Current point flight time: 00:00:00
 Total flight time: 00:00:00
 Total estimated time of one way: 00:01:52
 Total distance of one way: 202.015m

To Target(M):0.0

Altitude(M):0.0

H.Speed(M/S):0.0

V.Speed(M/S):0.0

Editing Mission

- 0
- 1
- 2
- 3

1.Way point properties

Latitude	38.6905632019043
Longitude	-120.702842712402
Altitude	15
TurnMode	StopAndTurn
Forward_Flight_Speed	4
HeadingDegree	360
HoldTime	10

Latitude
Latitude of the selected way point.

+ - CLEAR SAVE OPEN

+1 +10 -1 -10

CANCEL UPLOAD **GO**

Imagery Date: 5/26/2014 1993 38°41'26.59" N 120°42'08.82" W elev 781 m Eye alt 1.06 km

GPS: | ATTI: | MODE: | 0 | Cancel

Future Developments

- Evolving FAA rules defining operational requirements hopefully by 2015
- New ASTM standards for small Unmanned Aircraft Systems
- Telemetry and real-time display development
 - Arduino based systems for data ingest and sampling control
 - Data overlays on the first-person view
- Data logging
 - Evaluation of existing systems for applicability
 - Development of hybrid logging and control systems
- Measurement sensor evaluations
 - RF field generated by UAV electronics
 - Vibration sensitivity and minimization through dampening
 - Motion effects on sensors

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Questions?

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