

# **Air Quality Monitoring Network Design Using Pareto Optimality Methods for Multiple Objective Criteria**

**Paul D. Sampson** <sup>(1)</sup>

with

**Peter Guttorp** <sup>(1)</sup> & **David M. Holland** <sup>(2)</sup>



<sup>(1)</sup> NRCSE, University of Washington

<sup>(2)</sup> U.S. Environmental Protection Agency

supported by a grant from the U.S. EPA

<http://www.nrcse.washington.edu/>

# Outline

1. Spatial Monitoring Network Design Objectives in the Statistics Literature
2. Air Quality Monitoring Objectives
3. Multiple Objective Monitoring Network Design
  - A. References to selected applications
  - B. Pareto Optimality approach
4. Summary

**Three components of an optimal spatial design problem  
(D.L. Zimmerman, Optimal spatial design.**

**In: *Encyclopedia of Environmetrics*)**

1. Specification of a design space of candidate sites (finite, or in principle, continuous spatial domain).
2. Specification of a model for the existing observations (if any) and the potential observations at candidate sites.
3. Specification of **an** optimality criterion.

# National and Regional Surveys

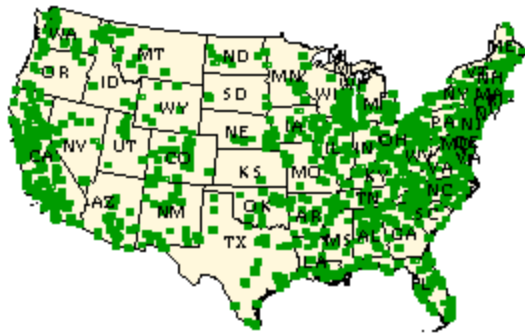
Program names link to pages with maps, measurements, and other program information.

## Table of Contents

<a href="#"><u>BBS</u></a>	<a href="#"><u>Breeding Bird Survey</u></a>
<a href="#"><u>CASTNET</u></a>	<a href="#"><u>Clean Air Status and Trends Network</u></a>
<a href="#"><u>EMAP</u></a>	<a href="#"><u>Environmental Monitoring and Assessment Program</u></a>
<a href="#"><u>FHM</u></a>	<a href="#"><u>Forest Health Monitoring</u></a>
<a href="#"><u>FIA</u></a>	<a href="#"><u>Forest Inventory and Analysis</u></a>
<a href="#"><u>NADP/NTN</u></a>	<a href="#"><u>National Atmospheric Deposition Program/ National Trends Network</u></a>
<a href="#"><u>NAMS/SLAMS</u></a>	<a href="#"><u>National Air Monitoring Stations/ State and Local Monitoring Stations</u></a>
<a href="#"><u>NSGN</u></a>	<a href="#"><u>National Stream Gaging Network</u></a>
<a href="#"><u>NAWQA</u></a>	<a href="#"><u>National Water Quality Assessment Program</u></a>
<a href="#"><u>NRI</u></a>	<a href="#"><u>National Resources Inventory</u></a>
<a href="#"><u>NS&amp;T</u></a>	<a href="#"><u>National Status and Trends (Mussel Watch Program)</u></a>
<a href="#"><u>PAMS</u></a>	<a href="#"><u>Photochemical Assessment Monitoring Stations</u></a>
<a href="#"><u>RAWS</u></a>	<a href="#"><u>Remote Automatic Weather Stations</u></a>
<a href="#"><u>SNOTEL</u></a>	<a href="#"><u>Snowpack Telemetry</u></a>

<http://www.epa.gov/cludygxb/programs/index2.html>

# National And Regional Surveys



<http://www.epa.gov/cludygxb/programs/namslam.html>

3-5 December 2001

EPA Spatial Data Analysis Technical  
Exchange Workshop

## NAMS/SLAMS- National Air Monitoring Stations/ State and Local Air Monitoring Stations

<b>Program Name (Acronym)</b>	NAMS/SLAMS
<b>Agency</b>	EPA,State &loc agen ow
<b>Year Initiated</b>	1979
<b>Measures</b>	AIR-criteria pollutnts, visibility/fine particulates, toxics
<b>Collection Source</b>	
<b>Point</b>	Yes
<b>Source</b>	No
<b>Transect</b>	No
<b>Other area</b>	No
<b>Locations for Data Collection</b>	5000 samplrs,3150 sites
<b>Temporal Interval</b>	Hourly,Pb&PM10 variable
<b>Sampling Design</b>	<u>Selected</u>
<b>Data Available</b>	Yes
<b>Accessible</b>	EPA reg offices,AIRS
<b>Extent for Reporting</b>	Primarily urban,some rura
<b>Annual Funding</b>	FY 96-\$36 M in fed fnds
<b>Cost per Site for Installation</b>	\$5 K-\$100 K per site
<b>Cost per Site for Op. &amp; Mgmt</b>	Avrg \$1 K per site/yrly
<b>Partners</b>	
<b>International</b>	No
<b>Agency</b>	EPA Regions
<b>State</b>	State agencies
<b>Local</b>	Local agencies,contractrs
<b>Authorities/Reason for Running Prg.</b>	40CFR58
<b>Users of Data per Year</b>	450
<b>Program Meets Metadata Standards</b>	No
<b>Expansion of Prog (Needed/Not)</b>	Not needed
<b>Contact Person</b>	David Lutz
<b>Phone #</b>	919-541-5476

# 1. Spatial Monitoring Network Design Objectives:

## Frameworks for optimal spatial design:

### 1. Exploratory, random sampling, and/or space-filling designs.

Nychka, D. and Saltzman, N. (1998), Design of air quality networks. In *Case Studies in Environmental Statistics*

### 2. Designs for estimating a regression function in a spatially correlated field (with known spatial covariance):

W.G. Müller (2000, *Collecting Spatial Data: Optimum Design of Experiments for Random Fields*)

R.L. Smith (NSF-CBMS Lecture Notes, in prep).

### 3. Designs for estimation of the spatial covariance or variogram:

W.G. Müller and D.L. Zimmerman (1999, *Environmetrics*)  
R.L. Smith (NSF-CBMS Lecture Notes, in prep).

### 4. Designs for optimal spatial prediction, including designs specifically concerned with **assessment of regulatory thresholds**: identification of sites or regions exceeding thresholds (for one or more pollutant measures) and/or the risk or expected cost of misclassifying sites according to a threshold (classifying a “contaminated” site as safe or vice versa).

## 2. Air Quality Monitoring Objectives

**Multiple scientific objectives** are explicit in current guidelines for air quality monitoring networks. Three perspectives:

**1. Four general purposes for the ambient air monitoring program are** (<http://www.epa.gov/oar/oaqps/qa/monprog.html>):

- to judge compliance with and/or progress made toward meeting ambient air quality standards;
- to activate emergency control procedures that prevent or alleviate air pollution episodes;
- to observe pollution trends throughout the region, including non-urban areas; and
- to provide data base for research evaluation of effects: urban, land-use, and transportation planning; development and evaluation of: abatement strategies and diffusion models.



## 2. Specific objectives of monitoring sites in the SLAMS network according to U.S. Code of Federal Regulations, Part 58, Appendix D are:

- to determine representative concentrations in areas of high population density;
- to determine highest concentrations expected to occur in the area covered by the network;
- to observe pollution trends throughout the region, including non-urban areas; and
- to determine general background concentration levels.

See also EPA guidelines (U.S.EPA, 1998, EPA-454/R-98-002):

- to determine the extent of air pollution transport into and out of an area.

## So, what does this suggest for numerical objective design criteria?

1. Criterion associated with maps of probability of exceeding standards (computed how?)
  2. Criteria assessing spatial prediction accuracy (kriging error, entropy)
  3. Utility functions for other criteria:
    - network representation of population
    - network representation of sources
    - Cost
- **Remark:** 1 & 2 above are achievable using recent methods of spatial analysis

➤ Many of these objectives assume some form of **prior information** regarding where:

- people live,
- pollutant sources are, and
- high and background levels of pollutant concentrations are expected.

➤ Information about where high and background concentrations may be expected requires, probably, a **combination of available monitoring data and air quality model predictions** in network design calculations.

➤ Statistical network design methodology has apparently never been recommended to attempt to meet these objectives.

From “**Guidance for Network Design and Optimum Site Exposure for PM<sub>2.5</sub> and PM<sub>10</sub>**” (EPA-454/R-99-022):

Network Design Philosophies: statistical methods accounting for correlation, model-based methods, random sampling, systematic sampling, judgmental sampling, heterogeneous strategies.

**“Monitoring networks for criteria pollutants always use judgmental sampling strategies that consider where source emissions are in relation to populations and which way the wind blows. ... Most of this guidance is based on judgmental network design, though it is expected that networks will involve more of the hybrid approach as they are evaluated as future PM<sub>2.5</sub> measurements and improved aerosol modeling techniques are developed.”**

### 3. Multiple Objective Monitoring Network Design:

- A. References to selected applications in publications
- B. Pareto optimality approach

## B. Pareto optimal designs:

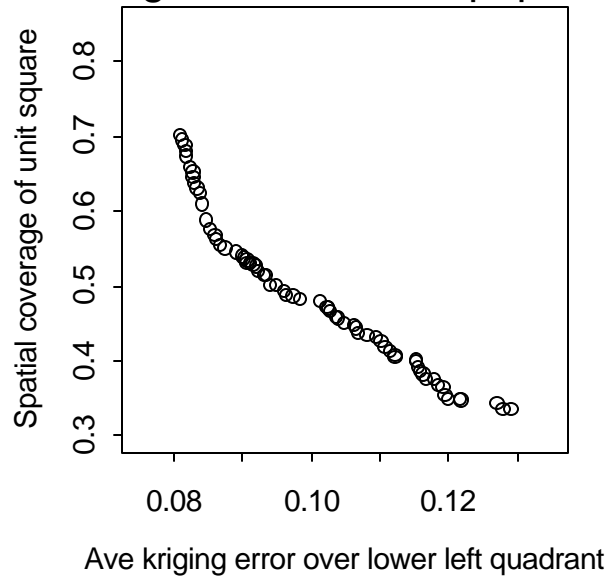
Alternative to optimization of a composite design criterion is to investigate the space of “Pareto optimal” designs.

Given a vector of  $n$  design criteria,  $X_1, \dots, X_n$ , a design having attained numerical criteria values  $a_1, \dots, a_n$ , is said to dominate another design attaining values  $b_1, \dots, b_n$ , if  $a_i \leq b_i$  for all  $i$ , and for at least one  $j$ ,  $a_j < b_j$ .

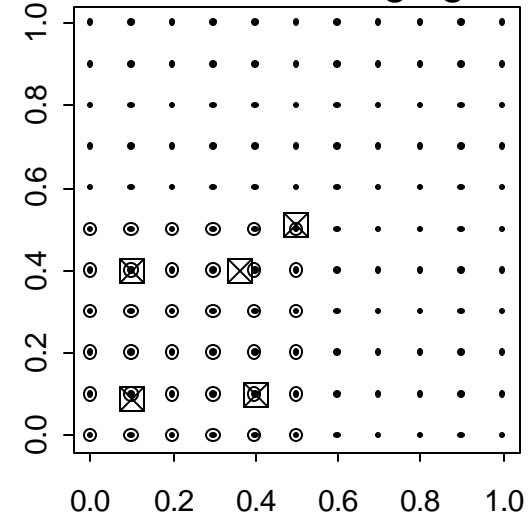
A design that is not dominated by any other is said to be Pareto optimal, and the Pareto optimal set or Pareto frontier is the set of all Pareto optimal designs.

Consideration of the Pareto optimal set will allow better understanding (compared with optimization of a single criterion) of the trade-offs necessary to obtain greater relative efficiency on given criteria.

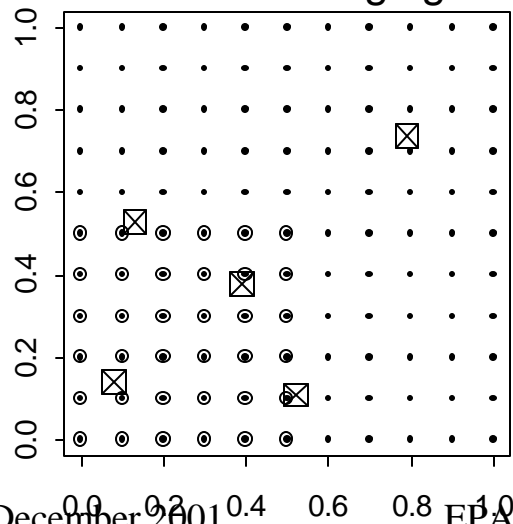
Estimation of Pareto Frontier  
from 1000 generations with pop size = 200



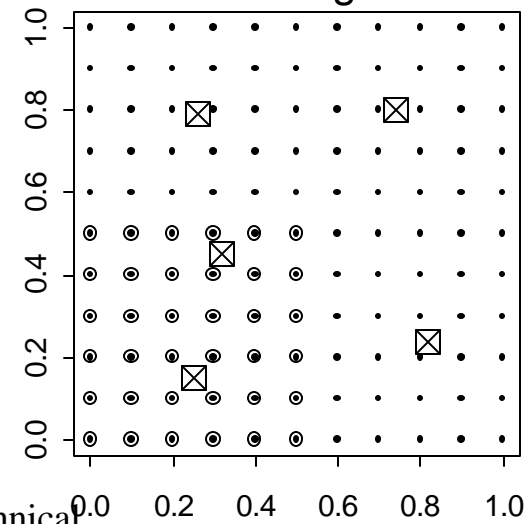
Pareto Frontier Design  
of minimum ave kriging error



Pareto Frontier Design  
of median rank kriging error



Pareto Frontier Design  
of least coverage criterion



## 4. Summary

- Fact: Multiple air quality monitoring objectives
- Some objectives require incorporation of prior information
  - In models and model-based estimates of errors for spatial estimation
  - In particular objectives of air monitoring that concern effects of pollutant sources & transport, and effects on human health
- Pareto optimal design calculations provide an effective way to make decisions in the context of multiple objectives.
- Evolutionary computation algorithms provide feasible tools for Pareto optimization.